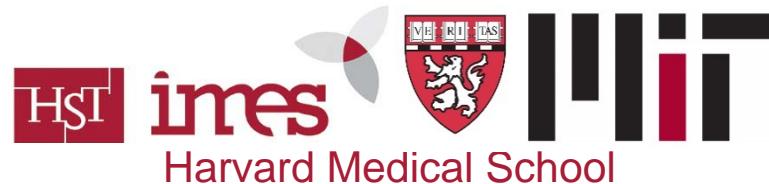


Dynamic Human-Centered Suit Design: A Computational and Experimental Method

Conor R. Cullinane

Massachusetts Institute of Technology



Lyndon B. Johnson Space Center – NASA

Dr. Leia Stirling, MIT

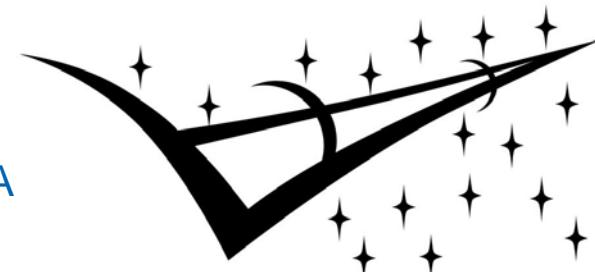
Richard Rhodes, NASA

Dr. Dava Newman, MIT

SPACE LIFE SCIENCES
SUMMER INSTITUTE

Man Vehicle Lab, MIT

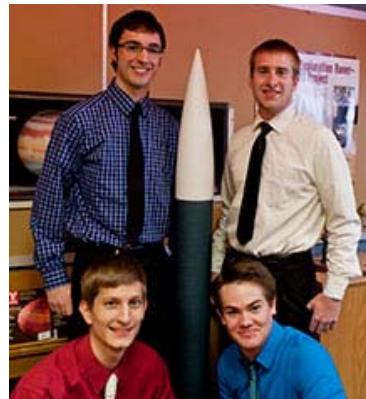
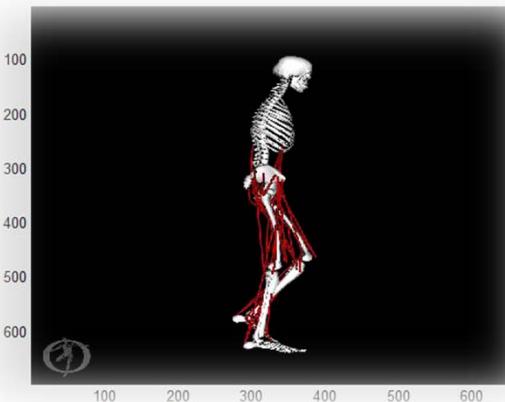
Advanced Space Suit Development Lab, NASA



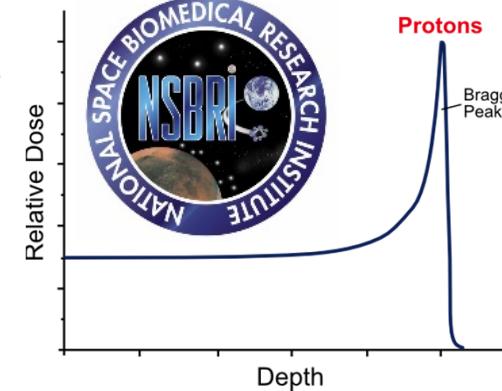
About Me

Clarkson
UNIVERSITY
defy convention

Wallace H. Coulter
School of Engineering



MASSACHUSETTS
GENERAL HOSPITAL



BROOKHAVEN
NATIONAL LABORATORY



Background

Why does NASA fund PSS mobility/agility research?



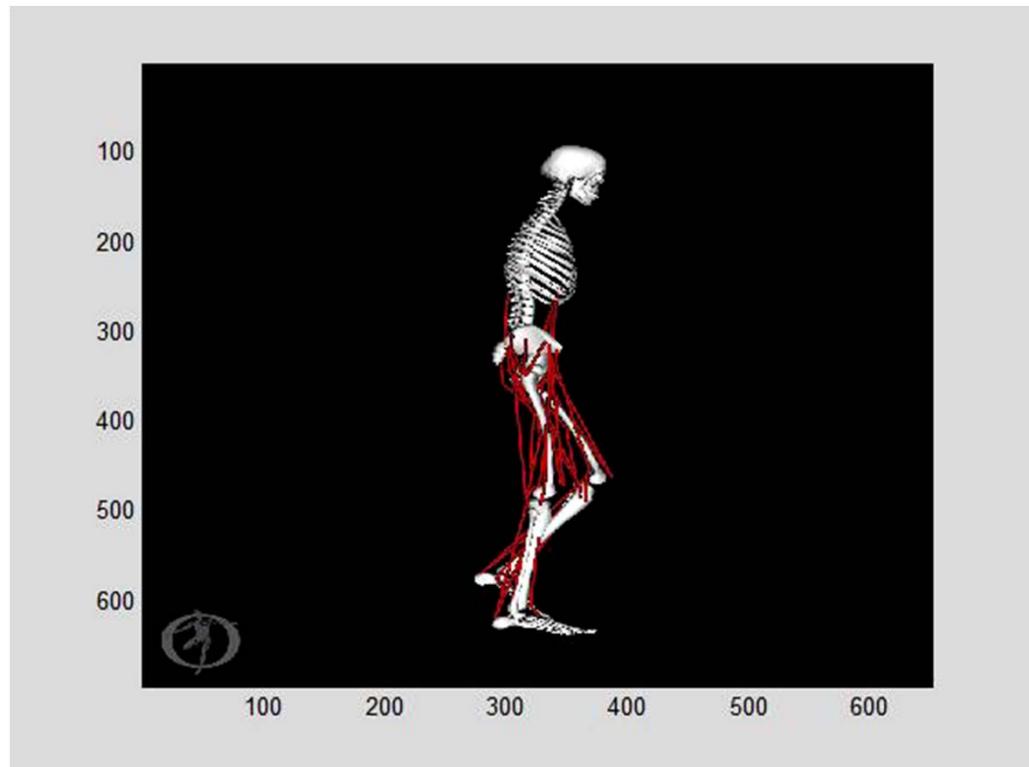
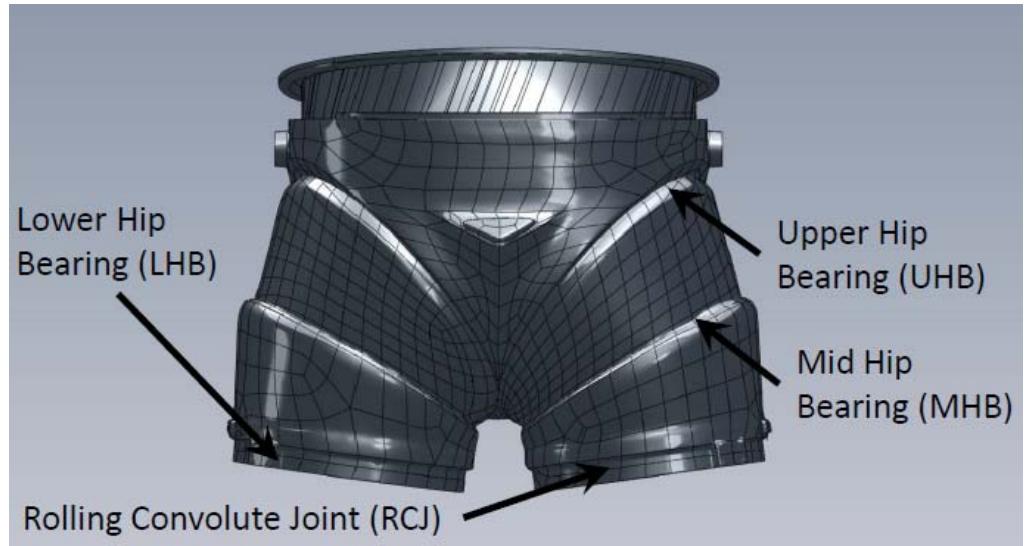
Objectives of Internship

- ❑ Research & compare possible software packages for an analysis pipeline
 - Musculoskeletal Modeling (OpenSim, AnyBody, LifeMOD, SANTOS)
 - CAD (AutoCAD, SolidWorks, ProE)
 - FEM (ANSYS, Creo2, Abaqus)
- ❑ Obtain current CAD representations of the hip joint assembly
- ❑ Develop the CAD representation to include high fidelity information
 - Obtain and input complete component characterizations
 - material characteristics, composition, weight
 - Determine and input bearing characteristics - Force-displacement (time variant curves)
Breakaway Force, steady state dynamics, and transitional dynamics
- ❑ Force plate gait test, fully suited, to obtain normal and shear force plate inputs for a musculoskeletal crewmember model

Methods/Procedures or Skills

- Geometry Details - Bearing Experiment
 - Isolate Individual Bearing
 - Dynamometer: Constant V or F
 - Understand Response Profiles
 - Repeat for Each Bearing, 1-Side

- Crewmember Details – Mobility/Agility Experiment
 - Normal Gait: Suited vs. Unsuited
 - GRF & ROM: 6DOF Force Plates & Vicon Motion Capture Systems
 - Planetary Surface Motion: Kneel & Recover, Side Step, Walking Backwards



Surface Scans

